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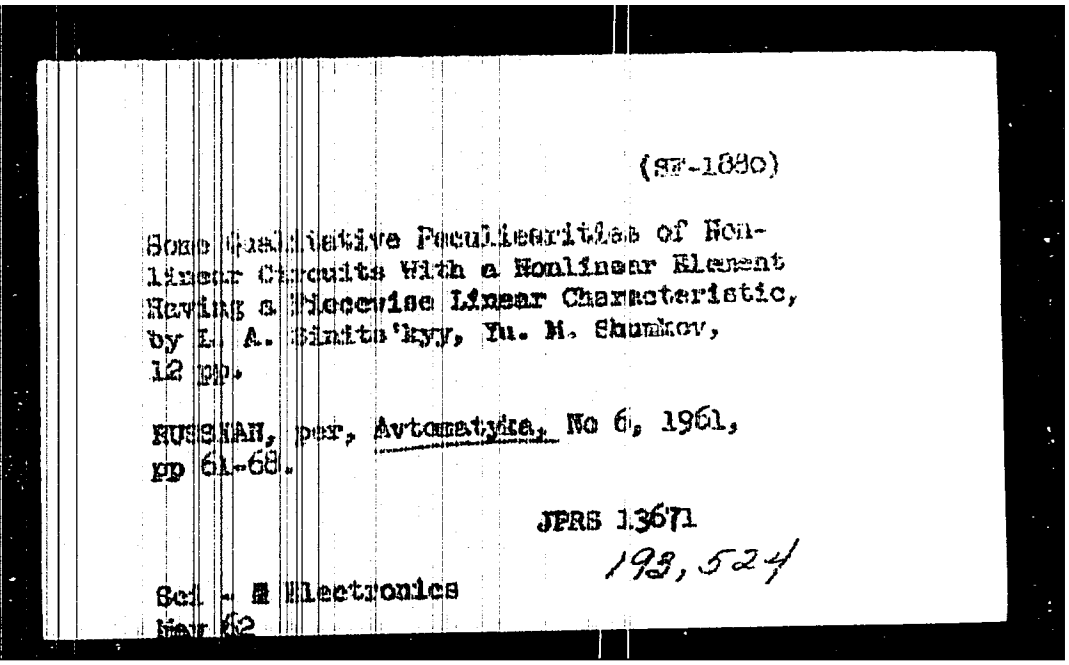

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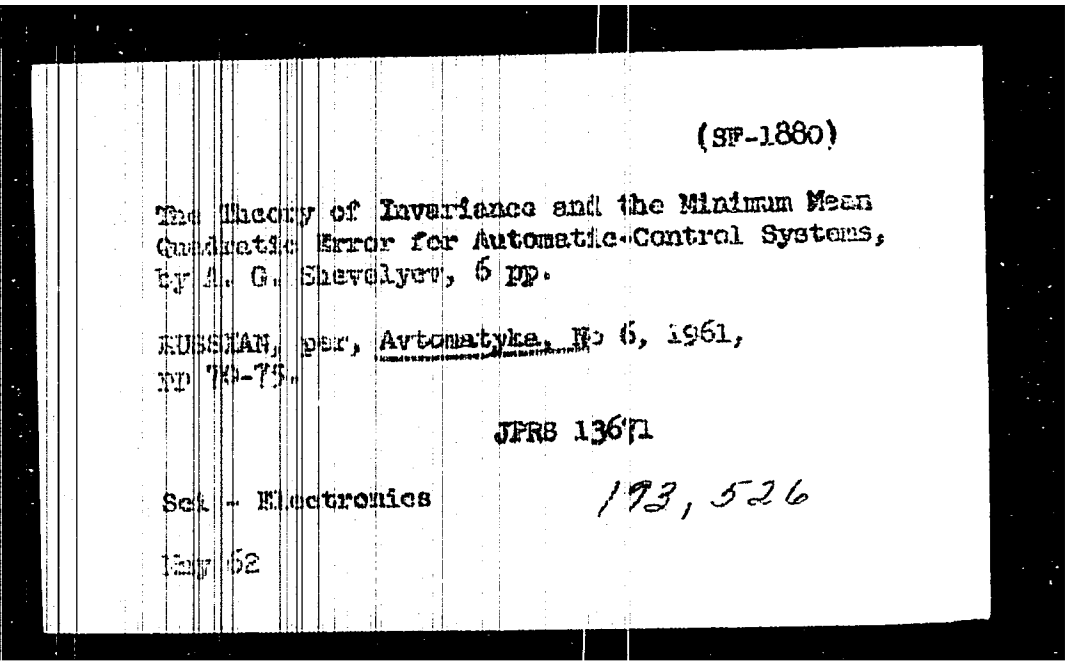

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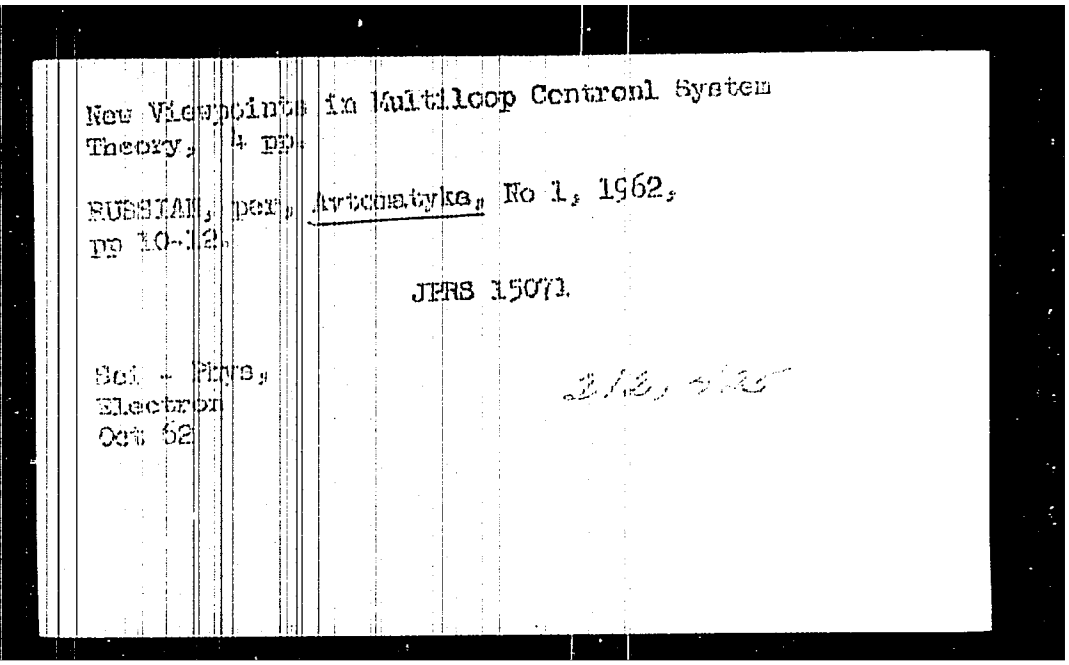

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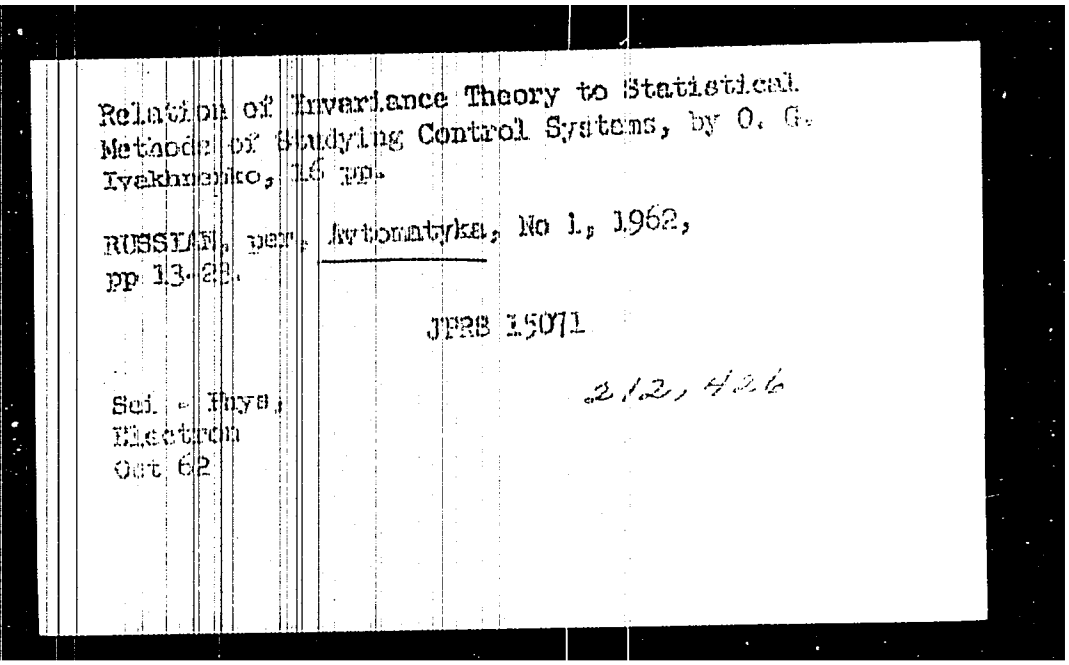

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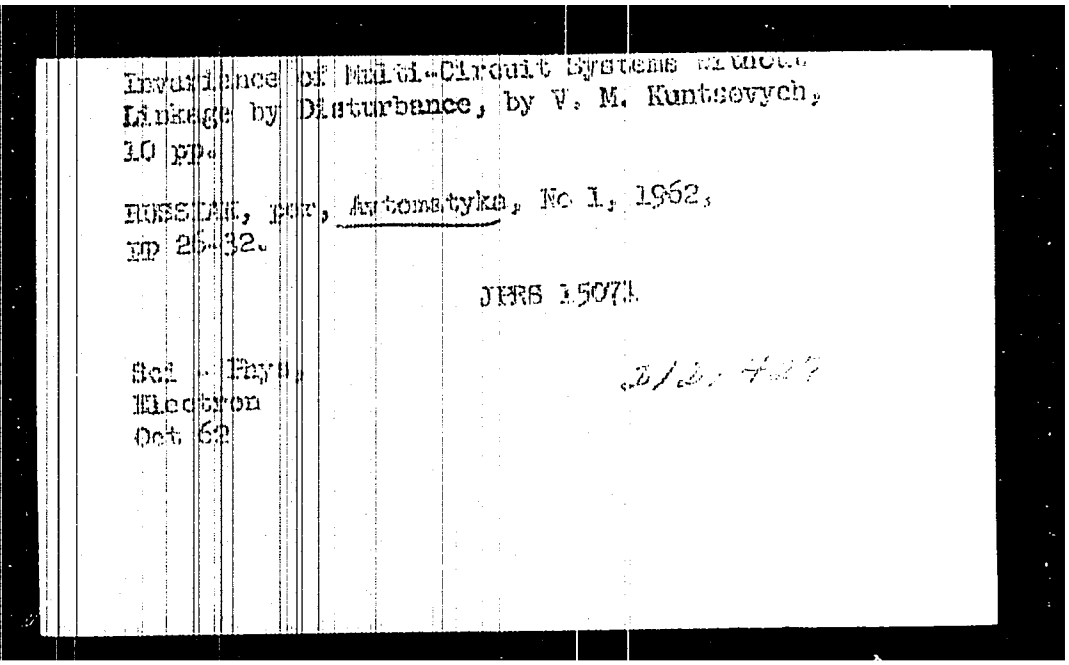

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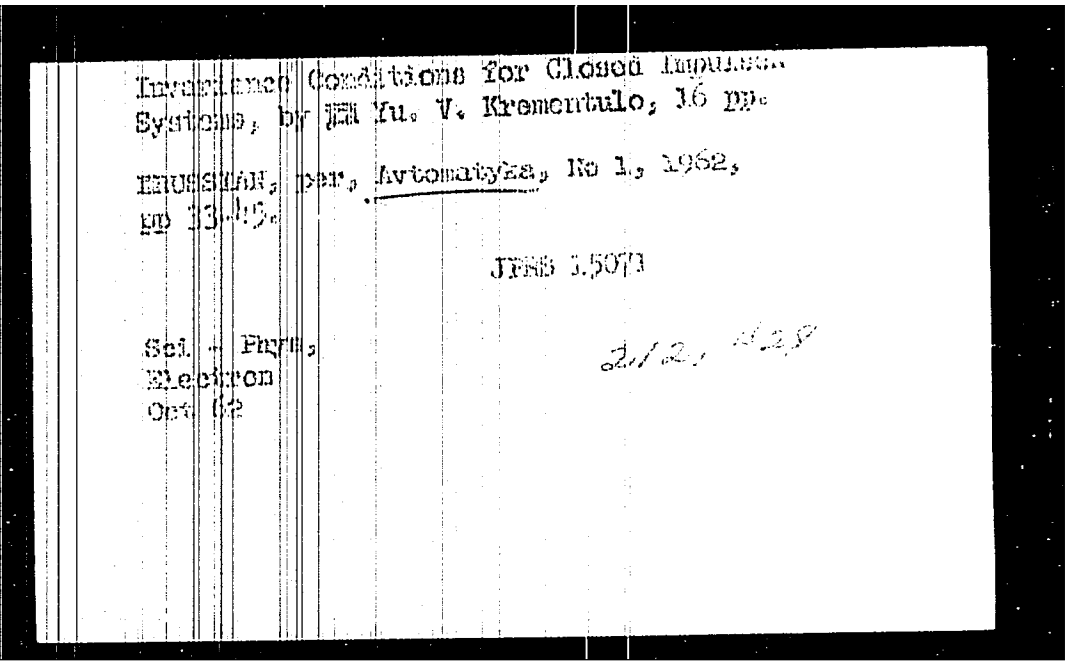

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SELF-ORGANIZING SYSTEM WITH XPOSITIVE FEED-BACKS,
BY O. G. IVAKHNENKO, 31 PP.

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JPRS 17688

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JPRS 17688

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DYNAMIC REGIMES OF STEP CONTROL SYSTEMS, BY P. Y. AKININ, 10 PP.

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JPRS 16837

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AUTO-OSCILLATION IN A RELAY EXTREMEAL, SYSTEM,
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EXPERIMENTAL INVESTIGATION OF SELF-ADJUSTING (EXTREMAL) SYSTEMS WITH A TRANSITORY MEMORIZING OF THE EXTREMUM, BY V. O. MITROSHYN, P. I. CHINAYEV, 14 PP.

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JPRS 16837

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PRODUCTION CONTROL BY COMPUTER, BY V. V. KLESHCHOV, 15 PP.

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JPRS 17899

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SECOND ALL-UNION CONFERENCE ON INVARIANCE THEORY
ANDITS APPLICATION TO AUTOMATIC SYSTEMS,
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CHOICE OF COMPOUND LINK COEFFICIENTS OF COMBINED CONTROL SYSTEMS, BY I. D, KOCHUBIYEVSKIY, 9 PP.

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JPRS 20486

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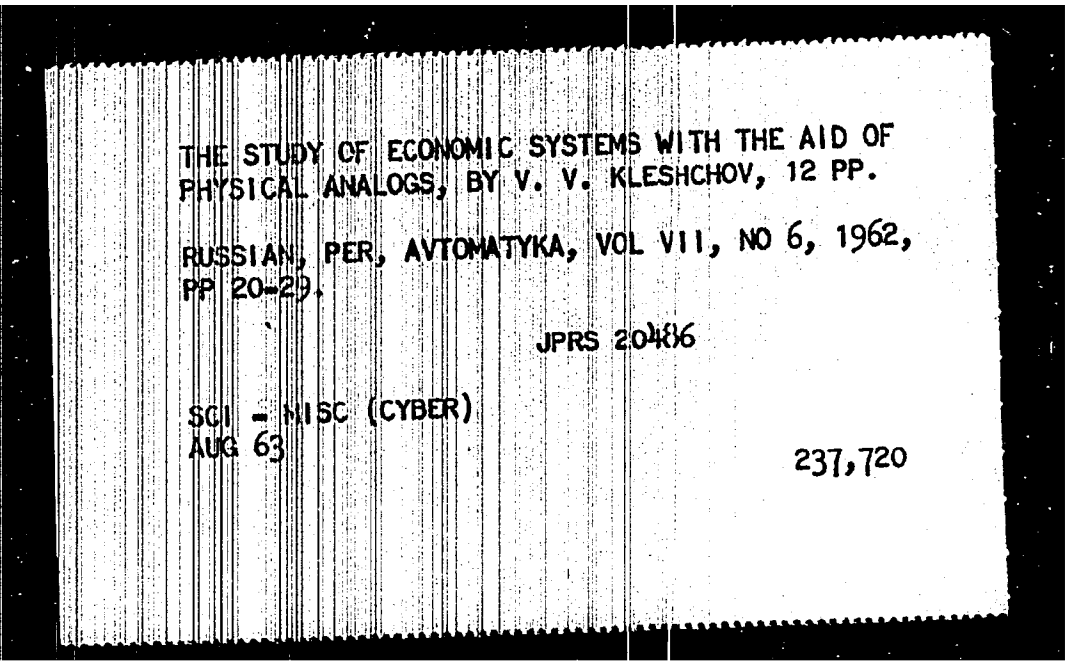

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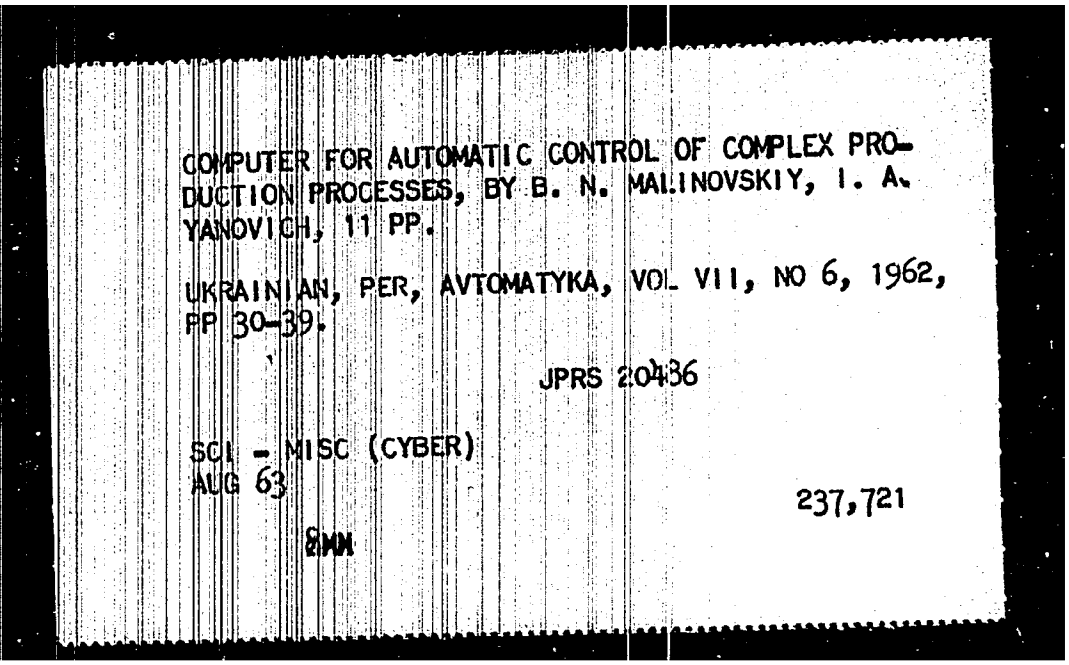

COMPUTER FOR AUTOMATIC CONTROL OF COMPLEX PRODUCTION PROCESSES, BY B. N. MALINOVSKIY, I. A. YANOVICH, 11 PP.

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A LEARNING SYSTEM WITH UTILIZES STATISTICAL
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JPRS 18406

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JPRS 18307

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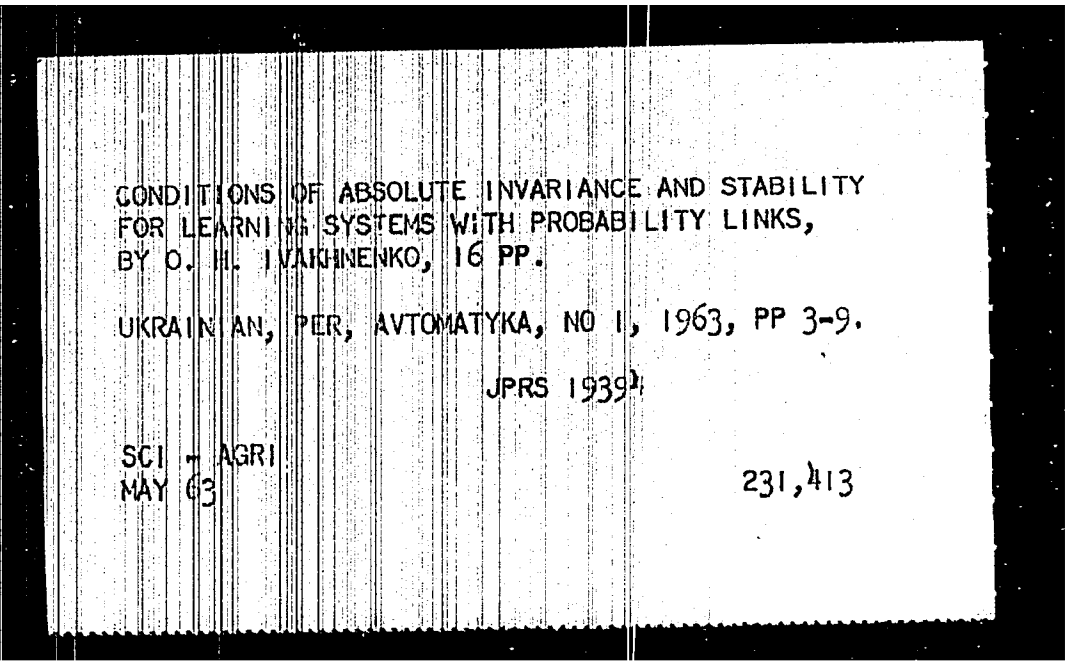

CONDITIONS OF ABSOLUTE INVARIANCE AND STABILITY FOR LEARNING SYSTEMS WITH PROBABILITY LINKS, BY O. H. IVAKHNENKO, 16 PP.

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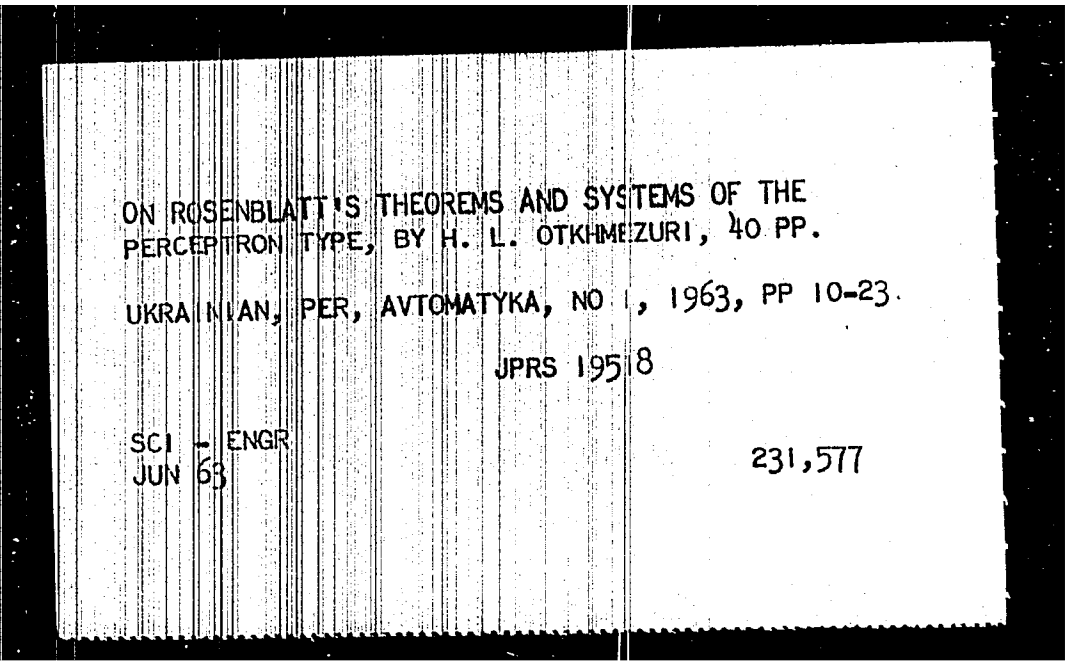

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IMPROVING THE ACCURACY OF THE DIGITAL INTEGRATOR,
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JPRS 19518

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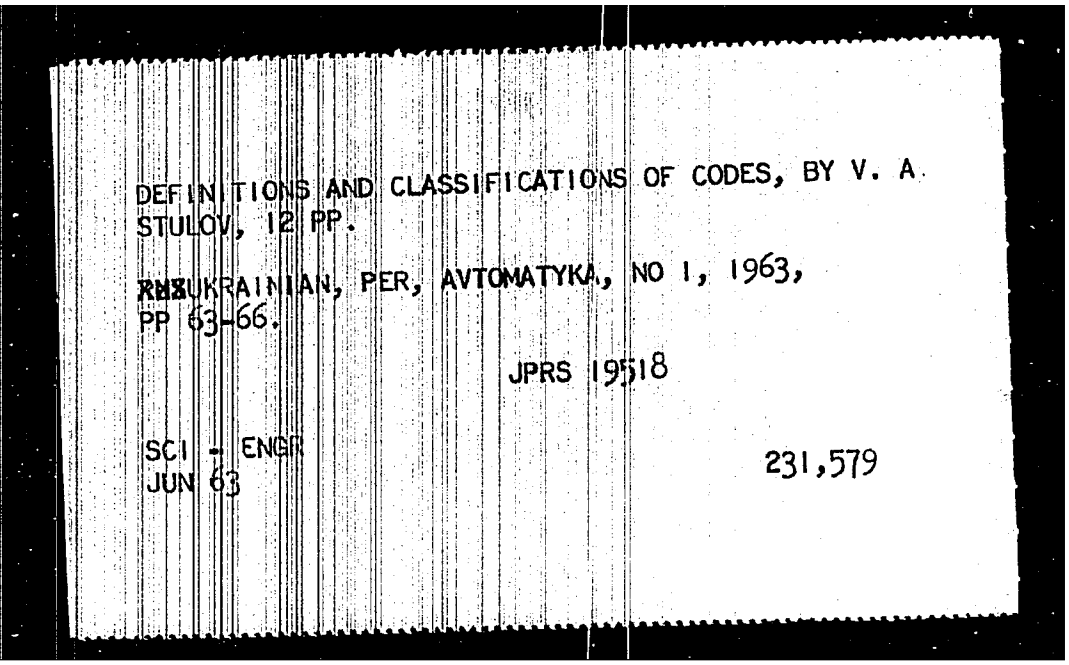

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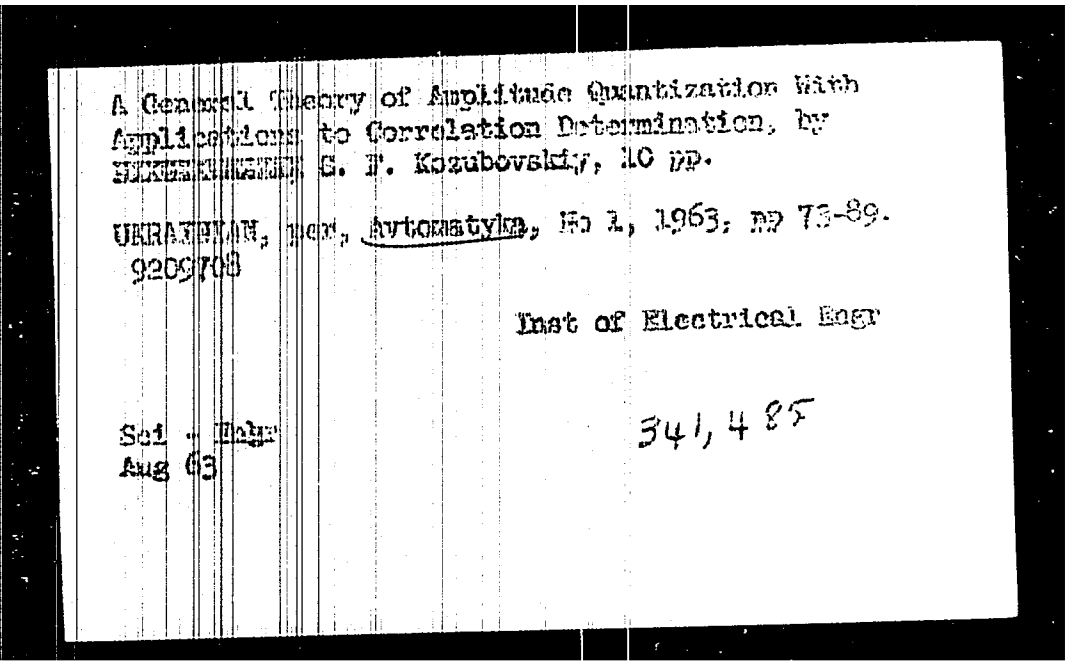

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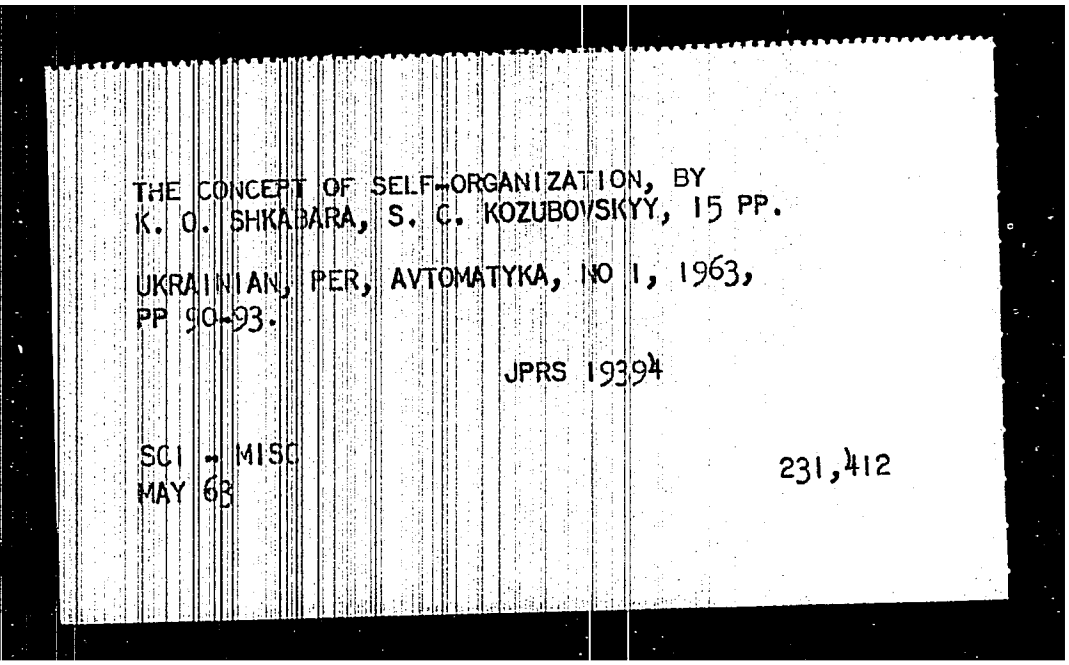

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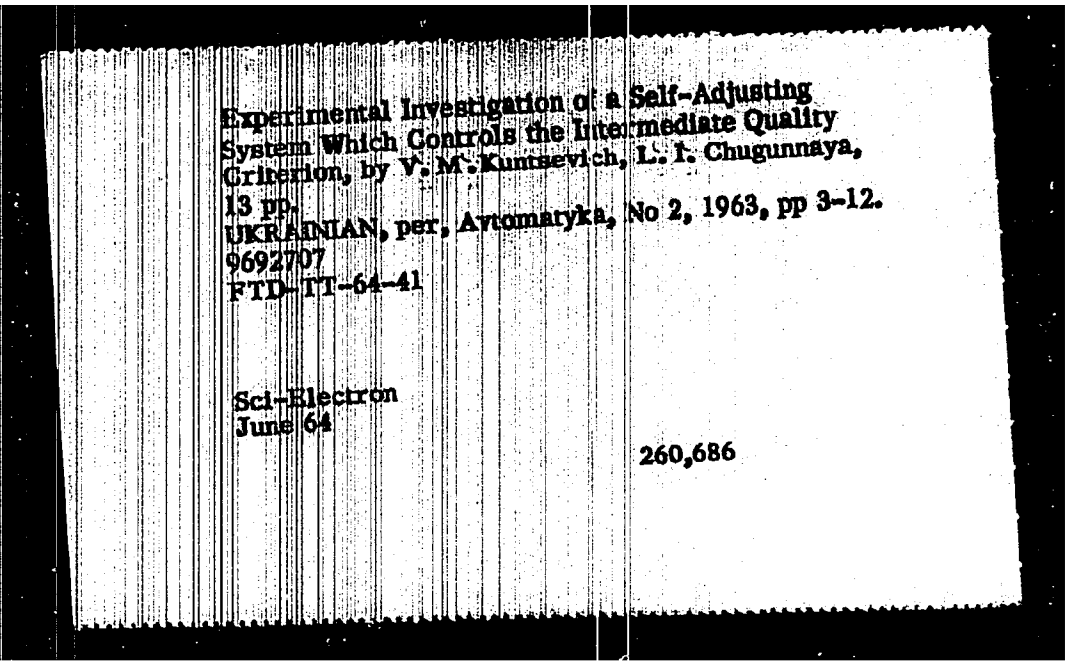

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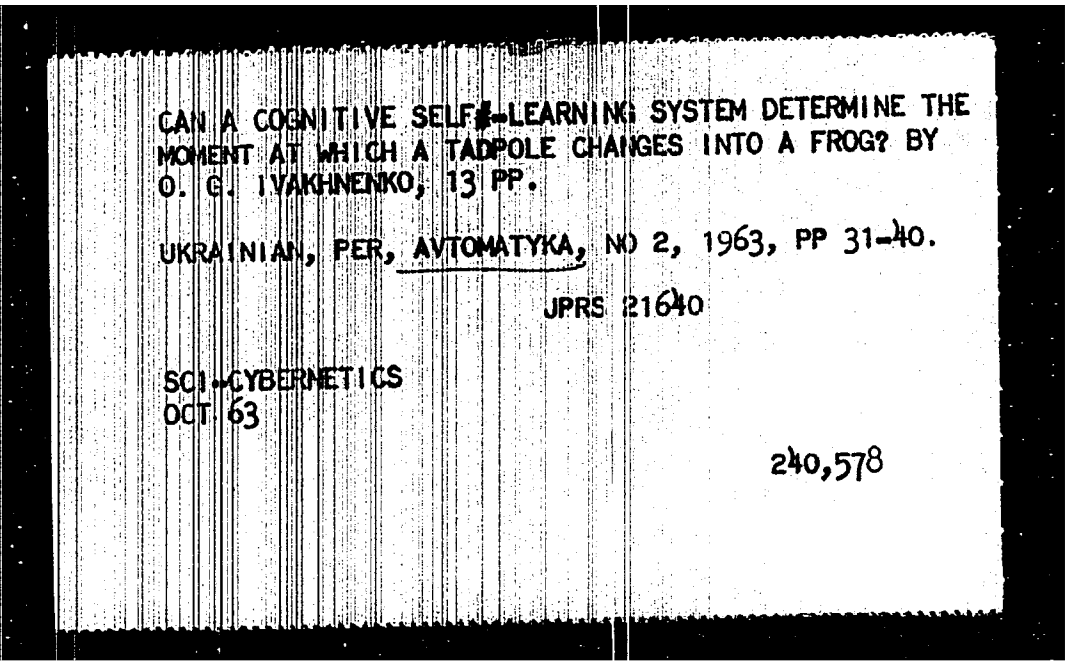

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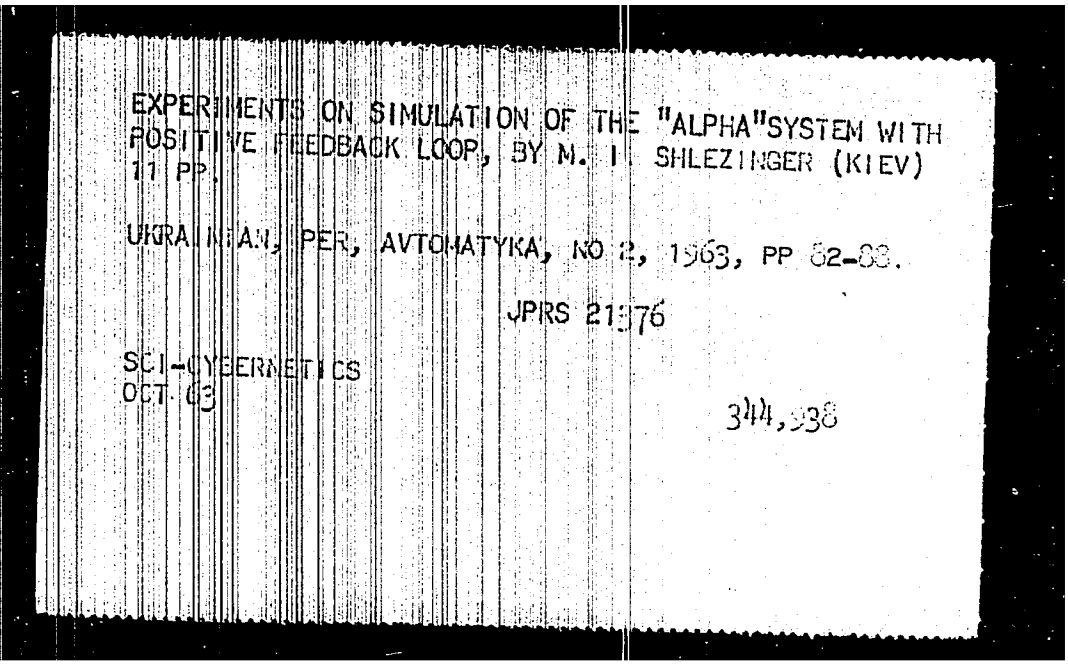

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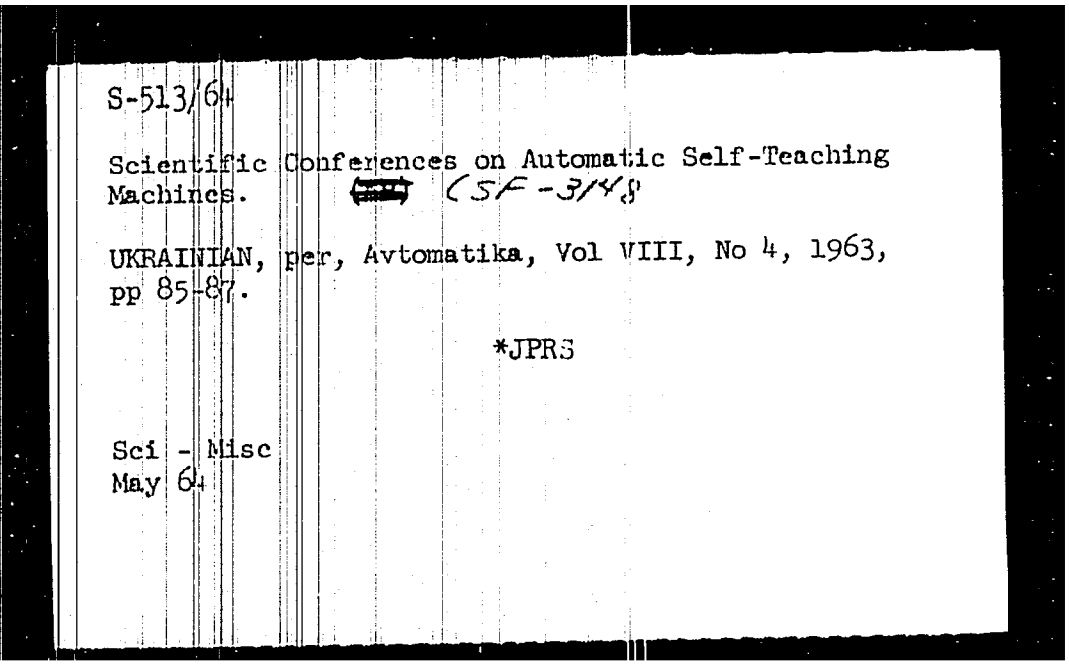

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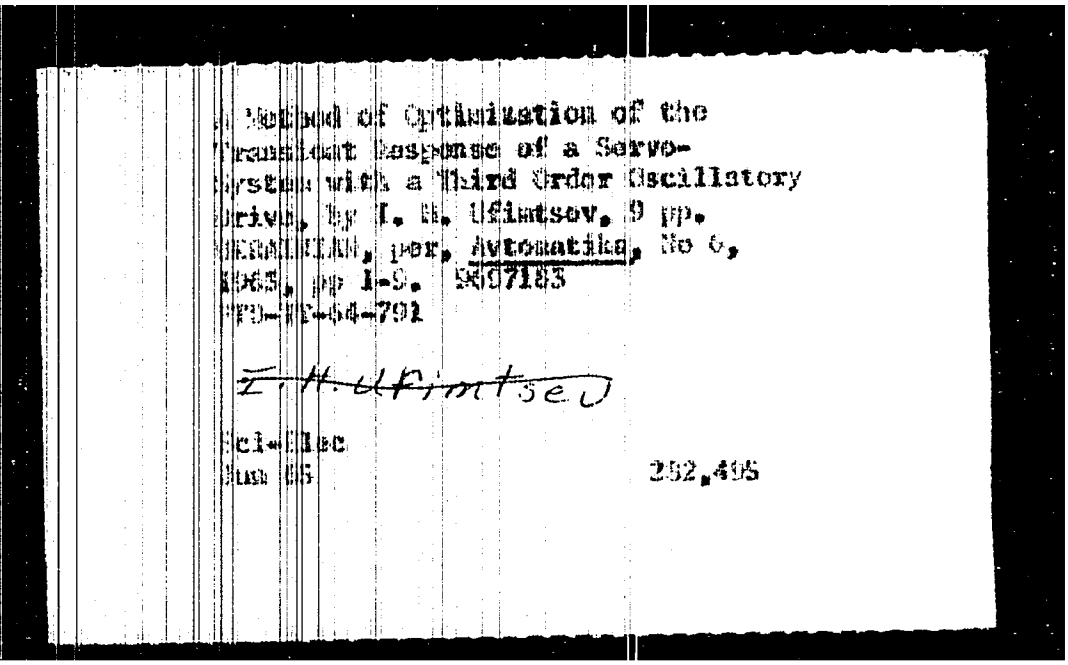

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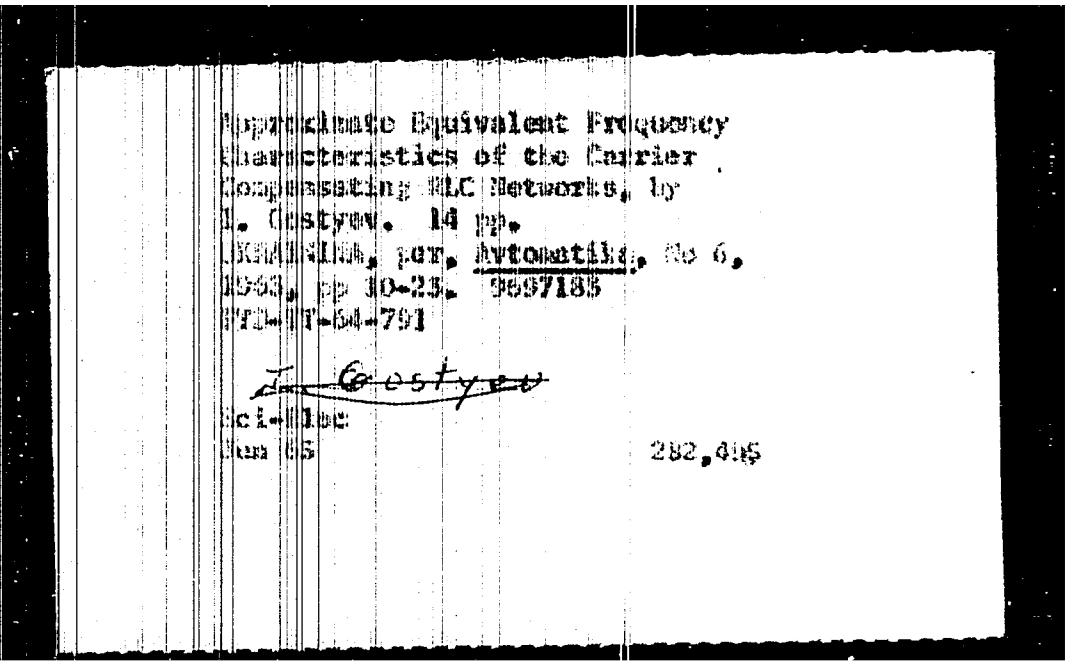

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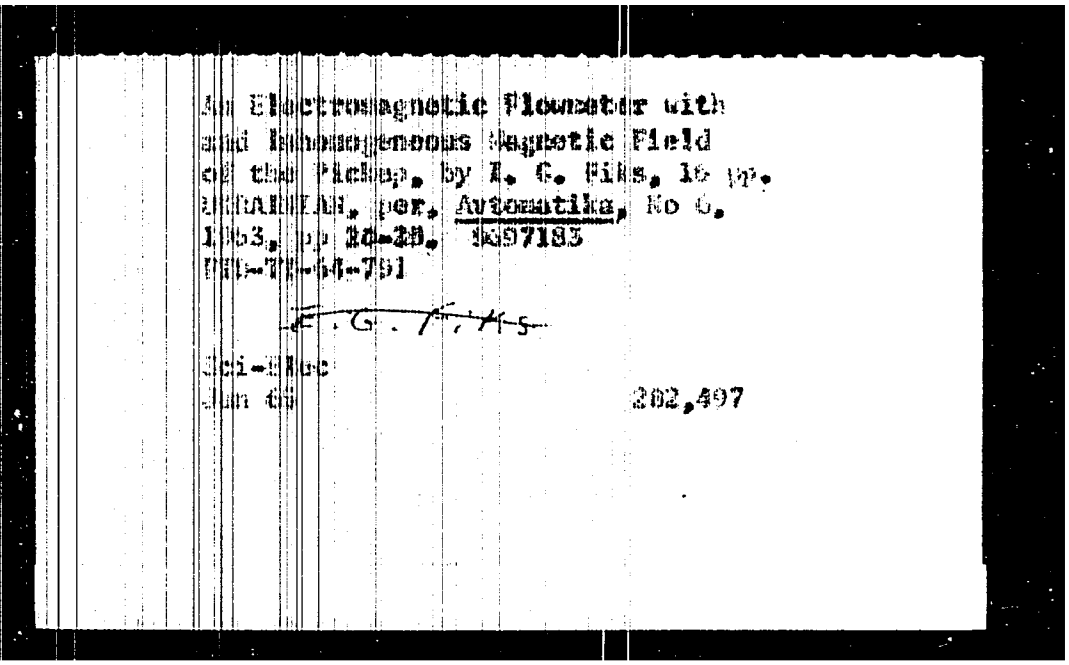

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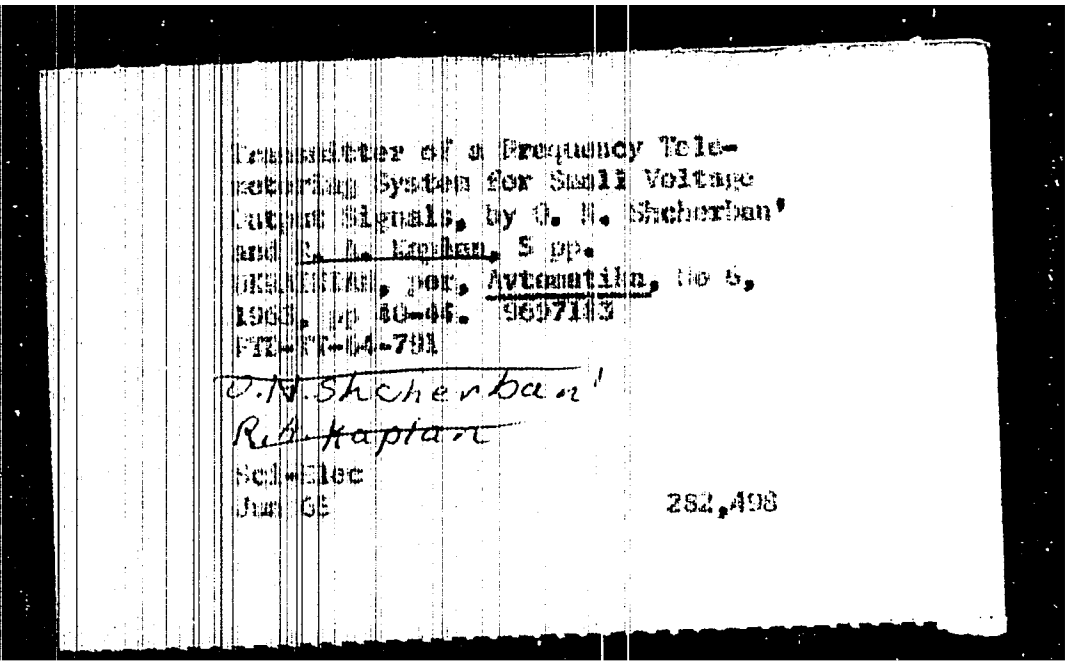

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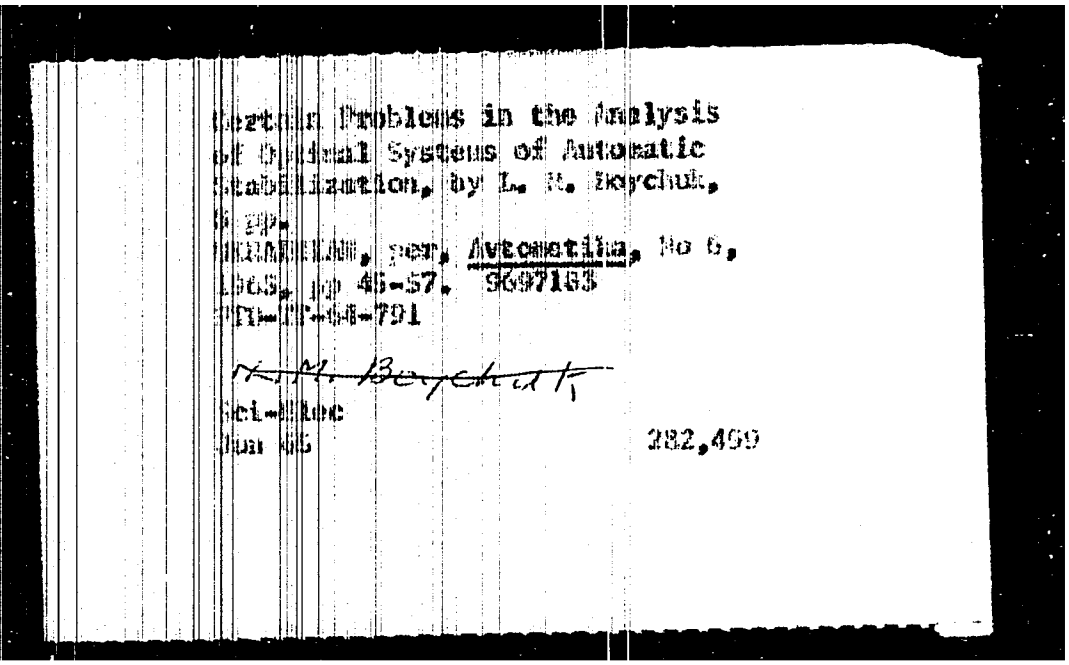

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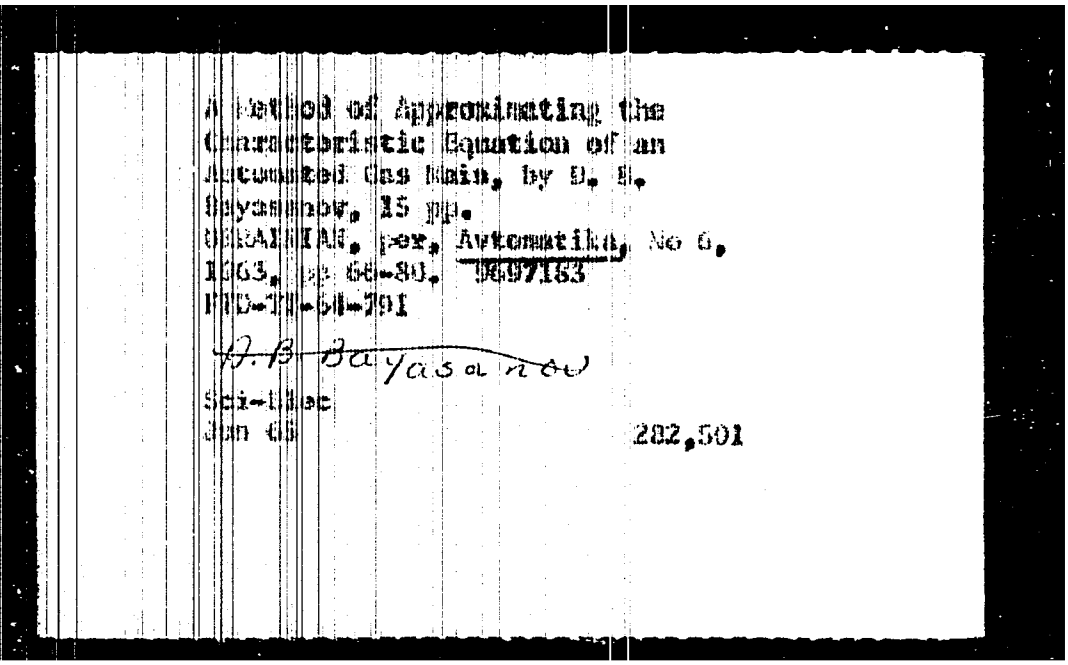

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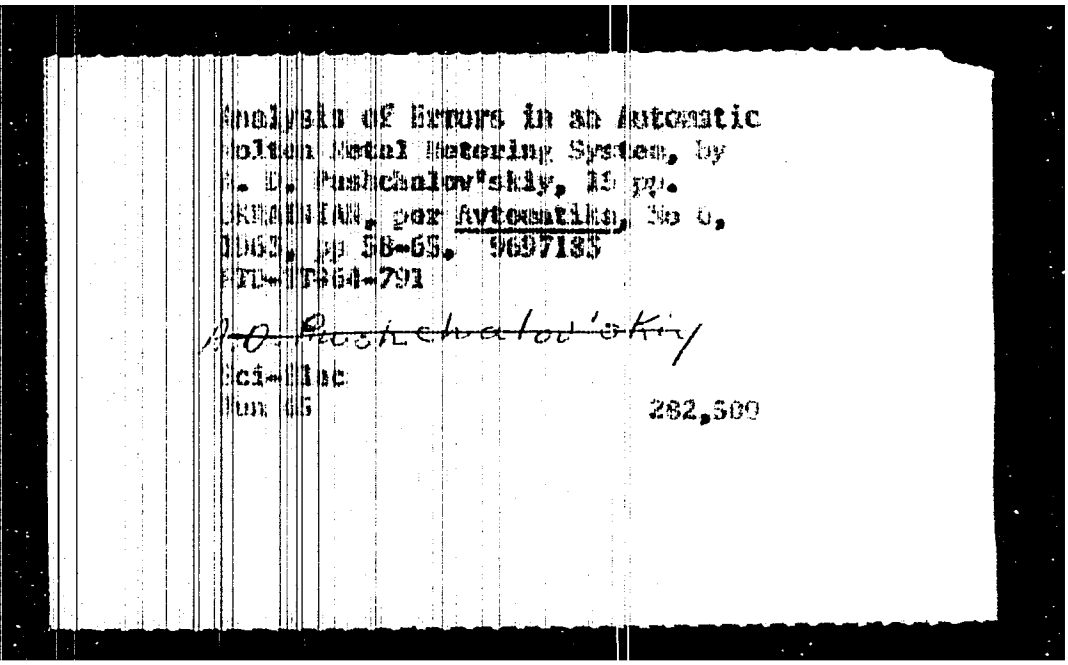

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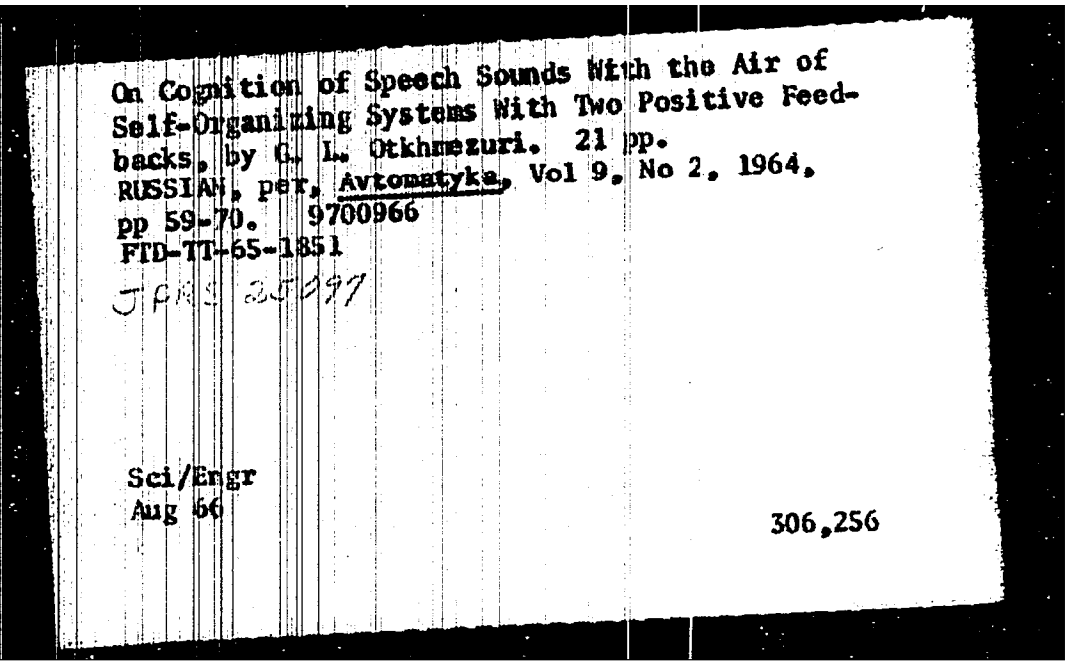

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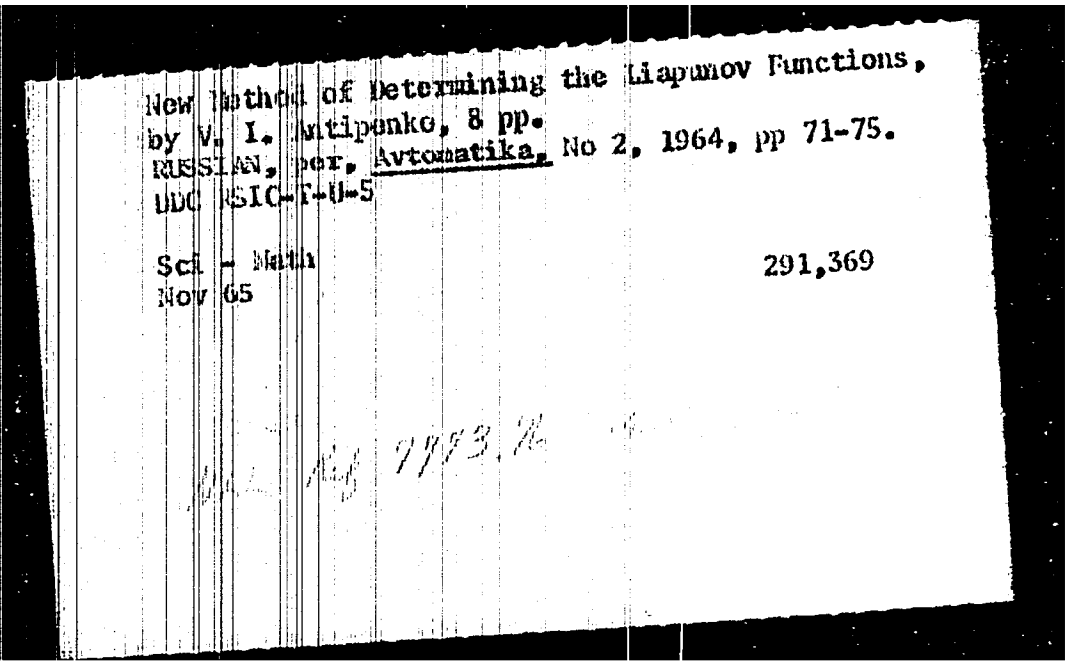

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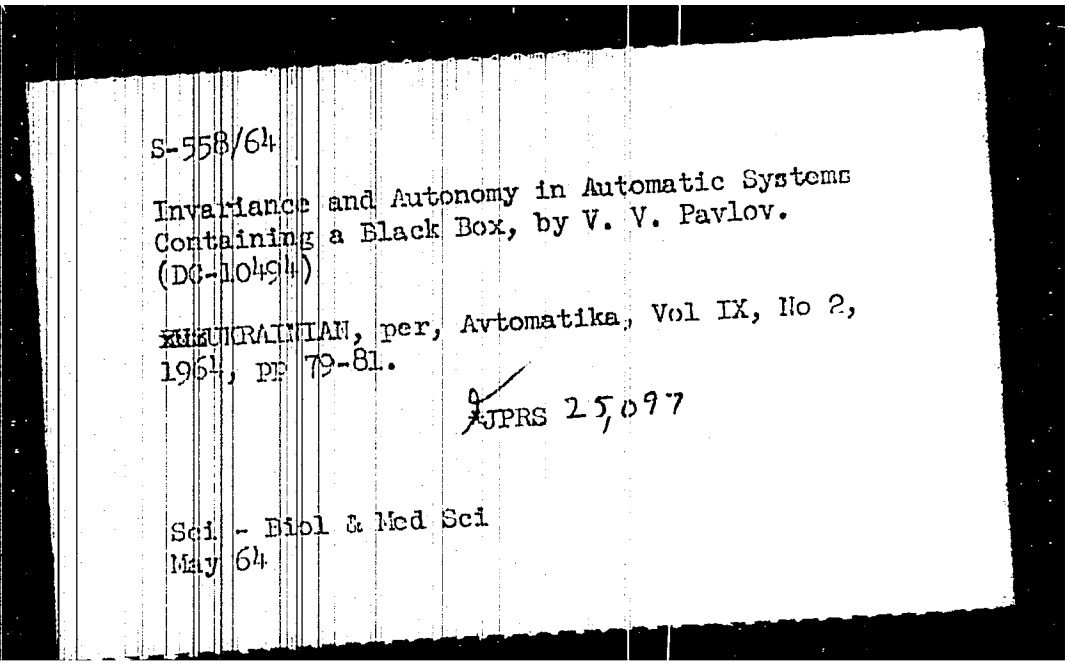

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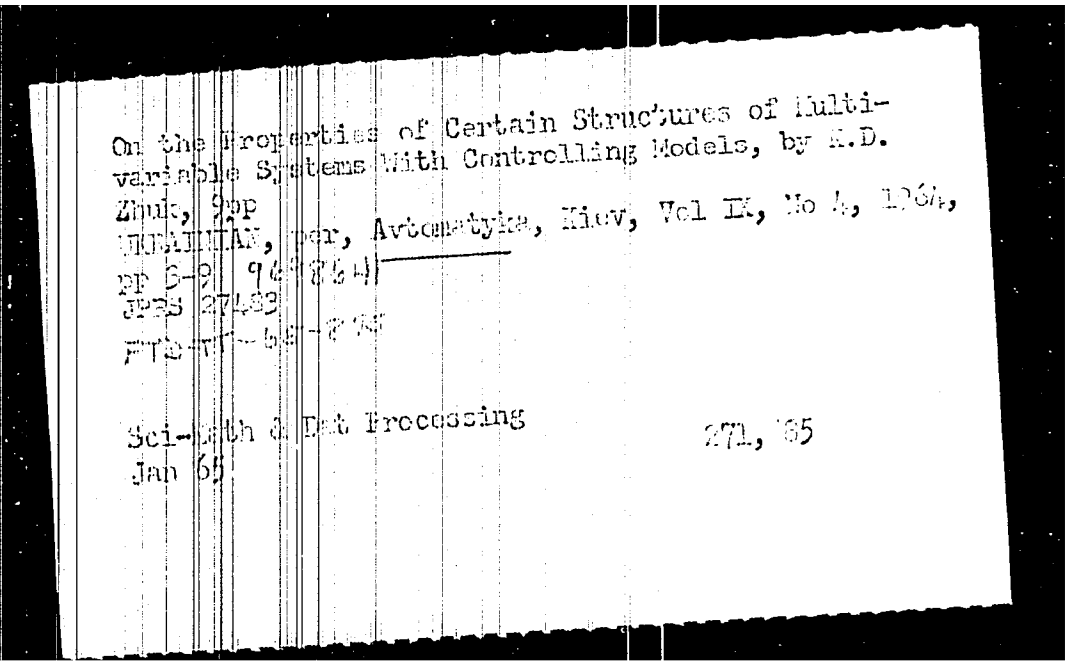

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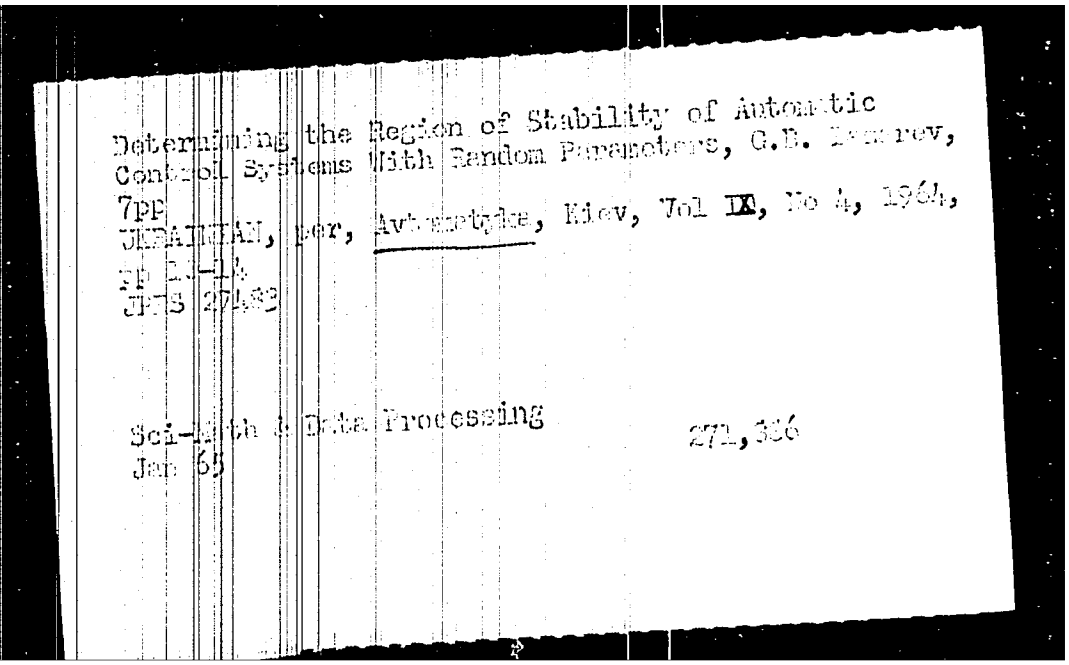

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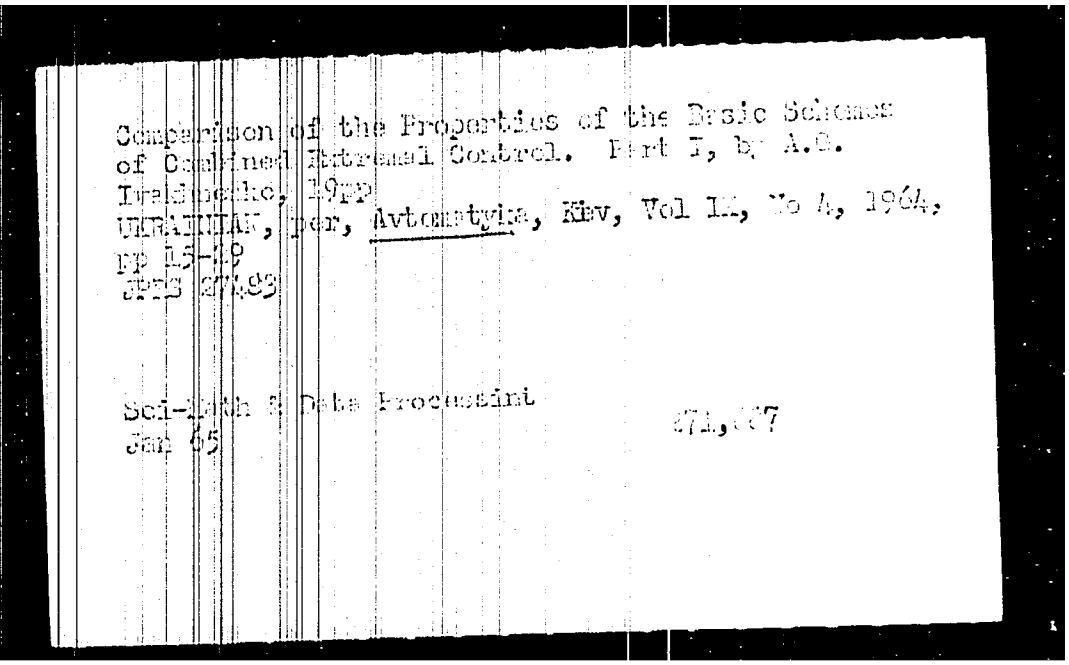

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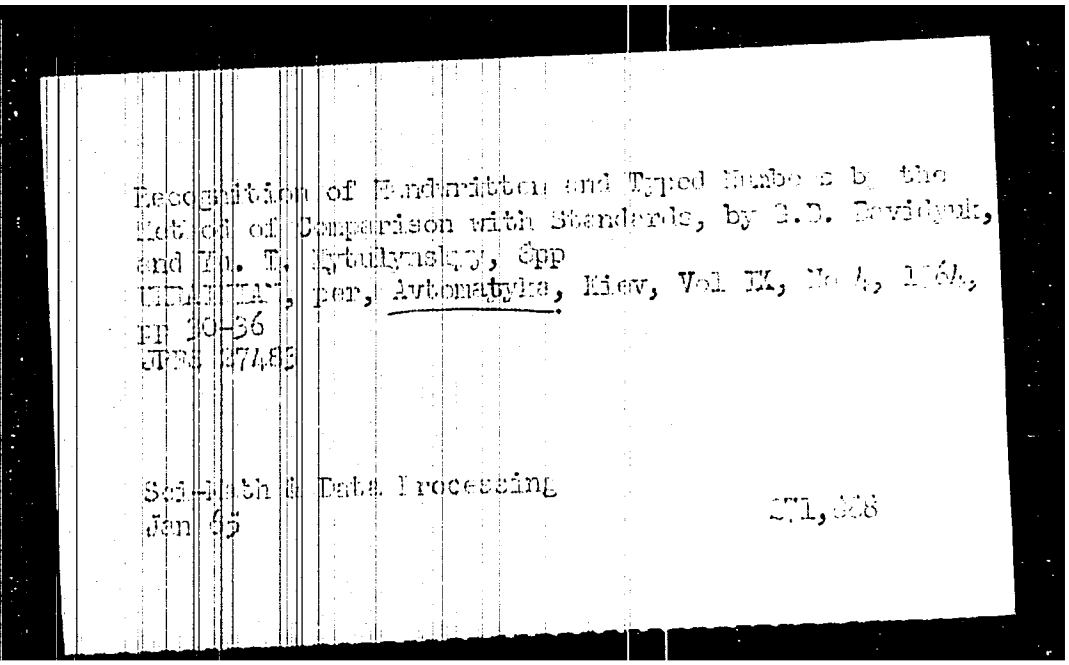

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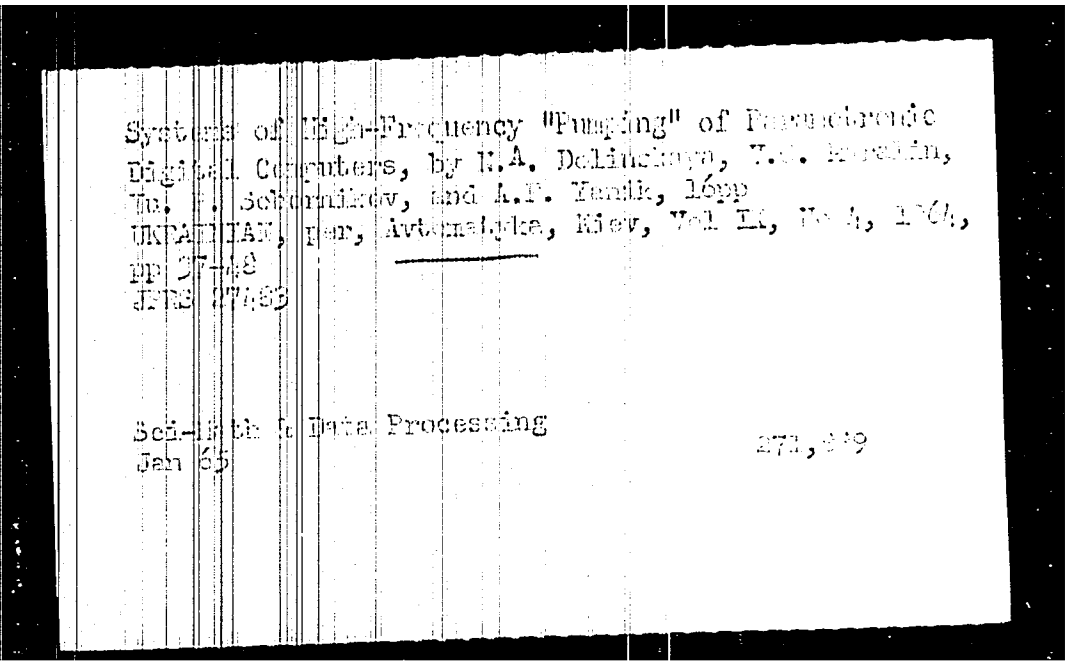

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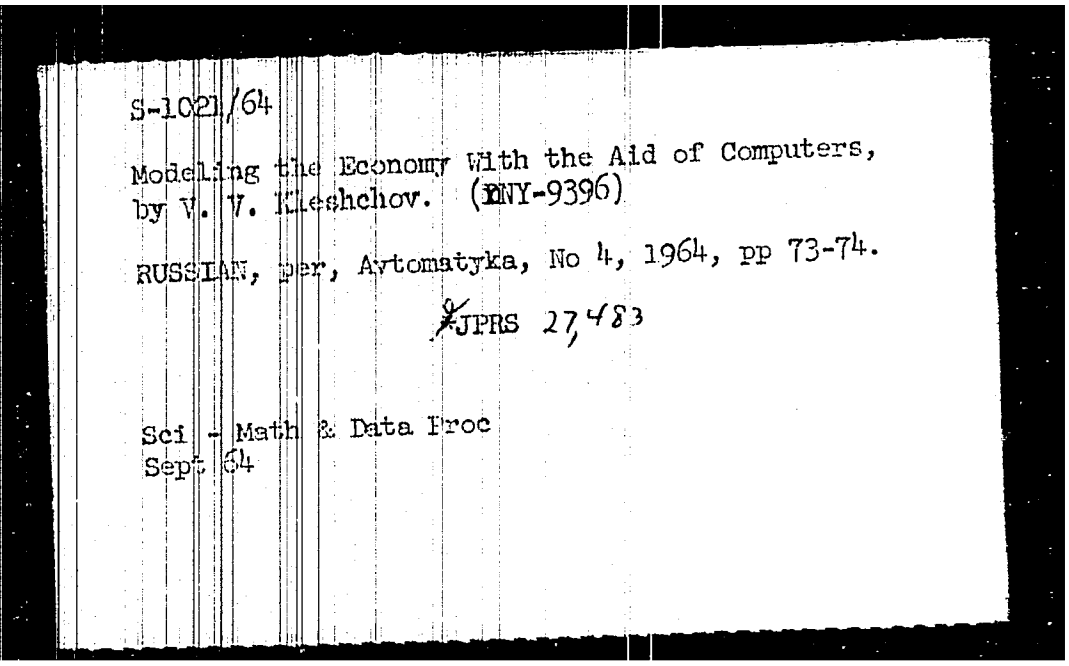

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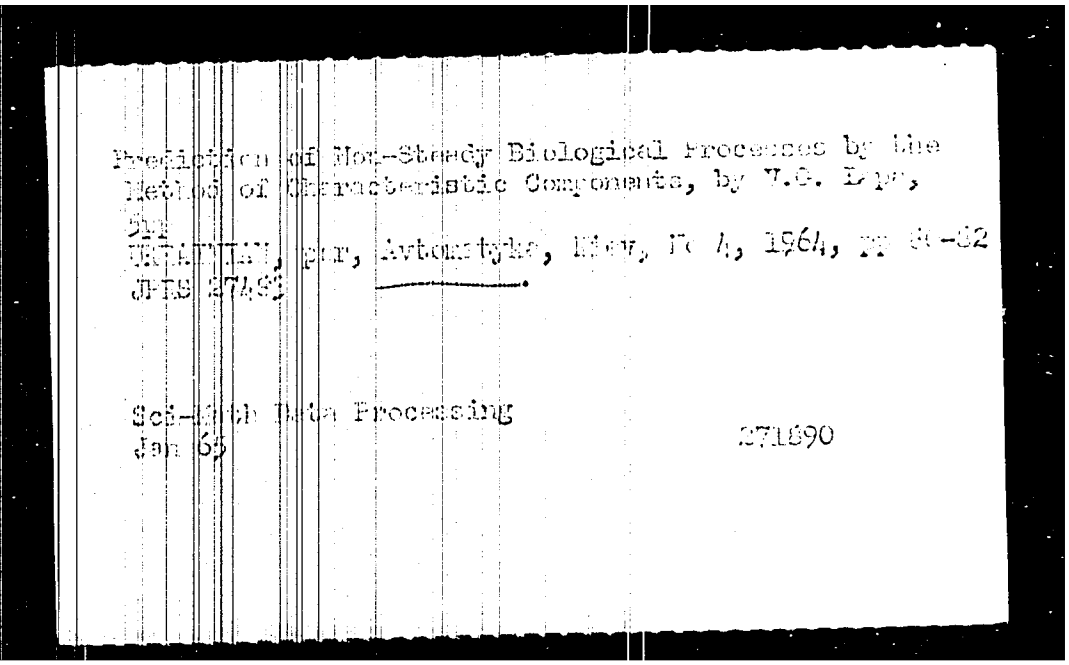

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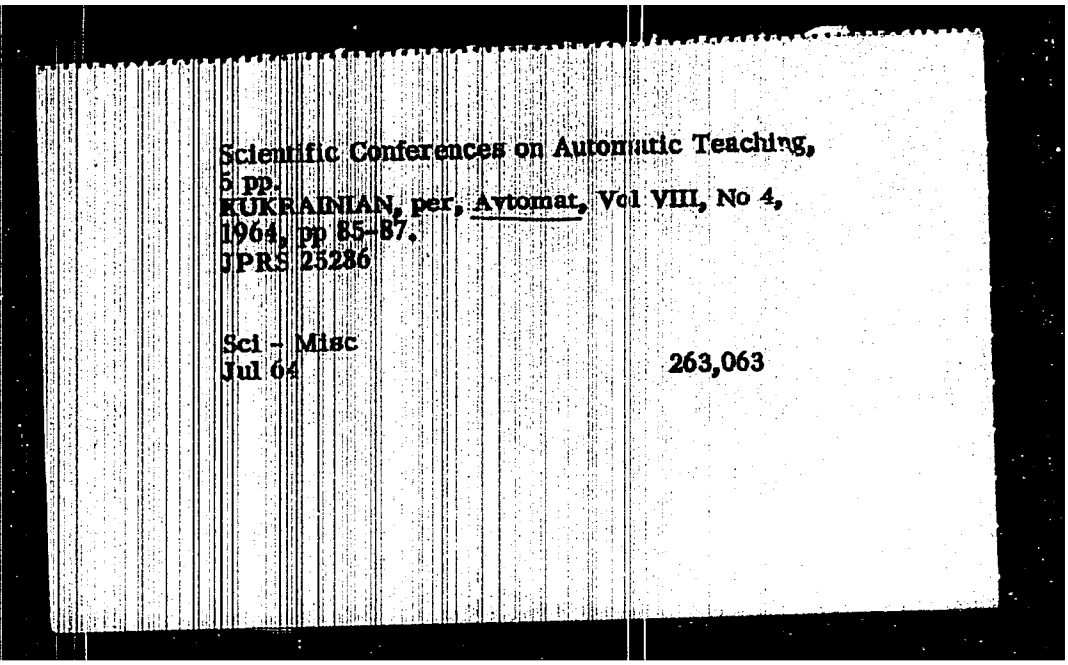

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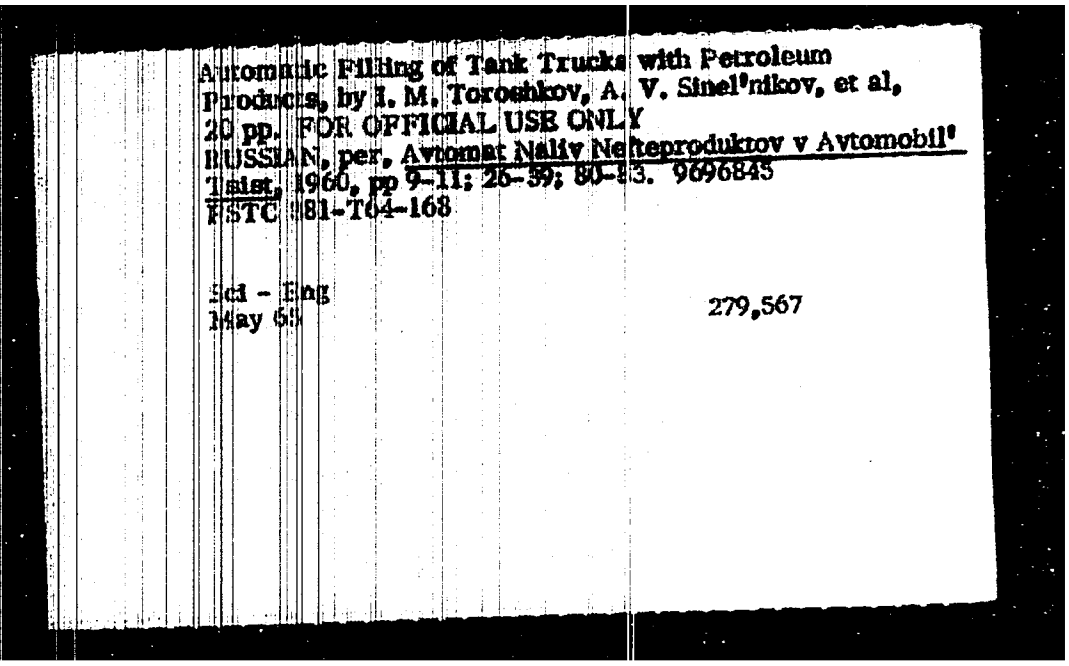

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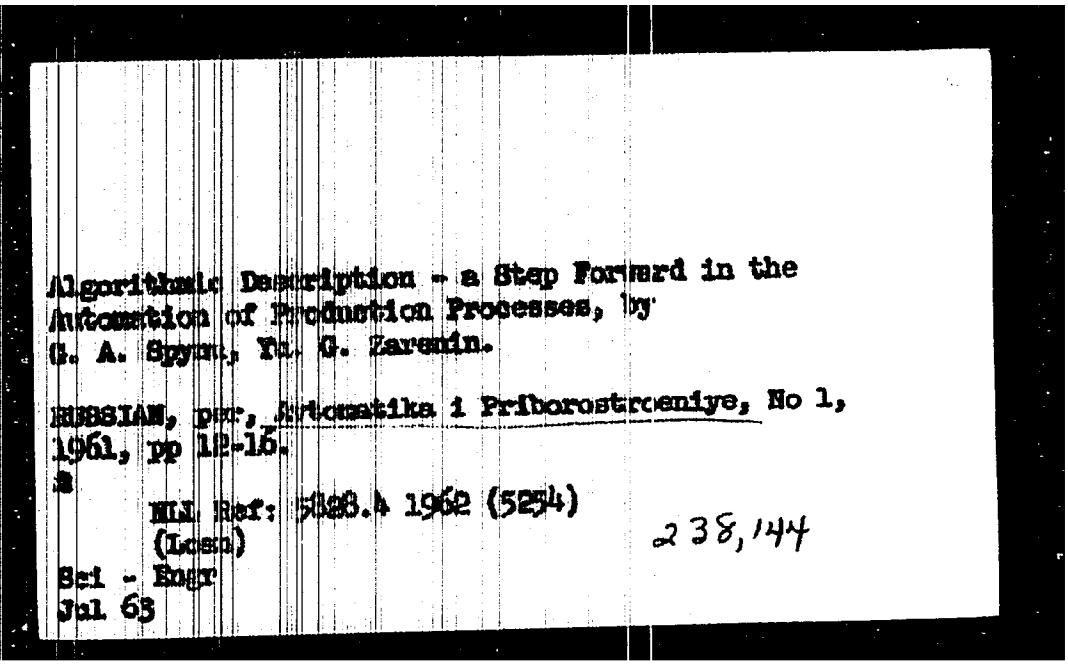

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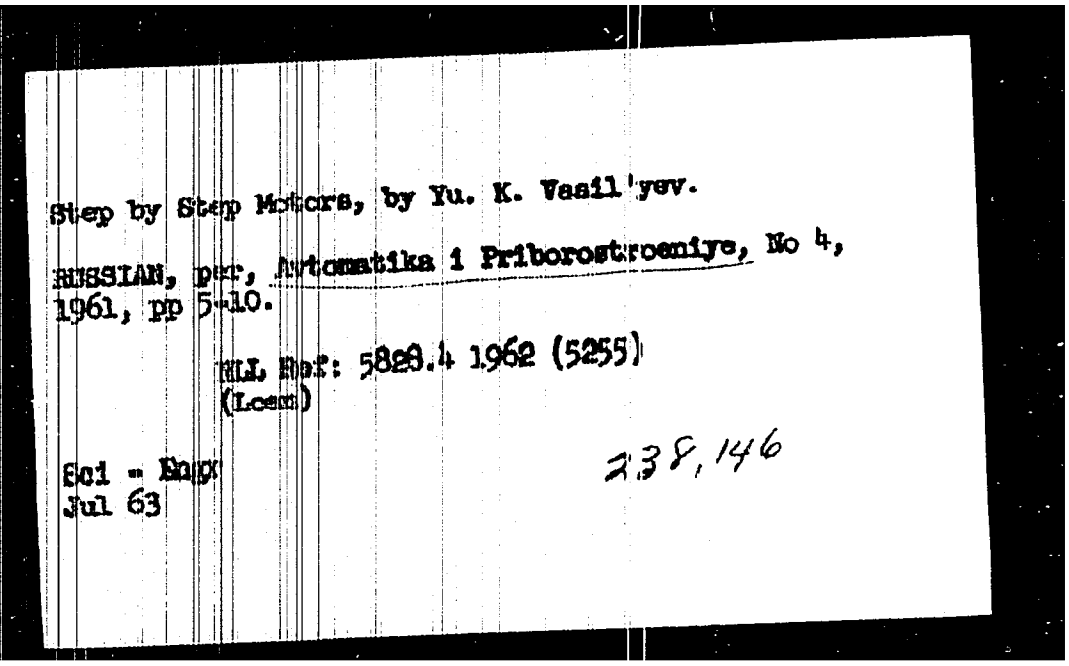

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